

III - APPLICATIONS OF QUANTUM MECHANICS

1. ANGULAR MOMENTUM

Motivation

In classical mechanics, the ordinary angular momentum three-vector is defined as

$$\vec{L} = \vec{x} \times \vec{p} = (x_2 p_3 - x_3 p_2) \hat{e}_1 + (x_3 p_1 - x_1 p_3) \hat{e}_2 + (x_1 p_2 - x_2 p_1) \hat{e}_3$$

In QM, inspired by the classical analog, we define the orbital angular momentum operator as

$$\begin{cases} L_1 = X_2 P_3 - X_3 P_2 \\ L_2 = X_3 P_1 - X_1 P_3 \\ L_3 = X_1 P_2 - X_2 P_1 \end{cases}$$

which of course is the same as $\vec{L} = \vec{X} \times \vec{P}$

or in index notation simply

$$L_i = \epsilon_{ijk} X_j P_k$$

Note that in the QM context X_i and P_i are operators. Since $[X_i, P_j] = i\hbar \delta_{ij}$, we do not have commutation issues in the definition of L_i above. For instance in the definition of L_1 , the operators X_2 and P_3 commute with each other.

From the canonical commutation relation

$$[X_i, P_j] = i\hbar \delta_{ij}$$

we immediately obtain

$$\left\{ \begin{array}{l} \text{(i)} \quad [L_i, P_j] = i\hbar \epsilon_{ijk} P_k \\ \text{(ii)} \quad [L_i, X_j] = i\hbar \epsilon_{ijk} X_k \\ \text{(iii)} \quad [L_i, L_j] = i\hbar \epsilon_{ijk} L_k \end{array} \right.$$

In fact

$$\begin{aligned} [L_i, P_j] &= [\epsilon_{ikl} X_k P_l, P_j] \\ &= \epsilon_{ikl} i\hbar \delta_{lj} P_k = i\hbar \epsilon_{ijk} P_k \end{aligned}$$

$$\begin{aligned} [L_i, X_j] &= [\epsilon_{ikl} X_k P_l, X_j] \\ &= \epsilon_{ikl} X_k (-i\hbar \delta_{lj}) \\ &= -i\hbar \epsilon_{ikhj} X_k = i\hbar \epsilon_{ijk} X_k \end{aligned}$$

$$\begin{aligned} [L_i, L_j] &= \epsilon_{iab} \epsilon_{jcd} [X_a P_b, X_c P_d] \\ &= \epsilon_{iab} \epsilon_{jcd} \{ X_c i\hbar \delta_{ad} P_b - X_a i\hbar \delta_{bc} P_d \} \\ &= i\hbar \{ \epsilon_{ihl} \epsilon_{jak} - \epsilon_{iah} \epsilon_{jkl} \} X_a P_k \\ &= i\hbar \{ -\epsilon_{ihl} \epsilon_{jak} + \epsilon_{iah} \epsilon_{bjk} \} X_a P_k \\ &= i\hbar \{ -\epsilon_{iah} \epsilon_{jak} - \epsilon_{iah} \epsilon_{bjk} \} X_a P_k \end{aligned}$$

$$\begin{aligned}
 [L_i, L_j] &= i\hbar \left\{ -\epsilon_{ikl} \epsilon_{jak} - \epsilon_{iah} \epsilon_{bjh} \right\} X_a P_b \\
 &= i\hbar \left\{ \epsilon_{ijk} \epsilon_{abk} \right\} X_a P_b \\
 &= i\hbar \epsilon_{ijk} \left\{ \epsilon_{kal} X_a P_b \right\} \\
 &= i\hbar \epsilon_{ijk} L_k
 \end{aligned}$$

The relation

$$[L_i, L_j] = i\hbar \epsilon_{ijk} L_k$$

is very remarkable and actually characterizes the Lie algebras of $so(3)$ and $su(2)$.

Definition: Any three operators J_1, J_2 and J_3 satisfying the commutation relations

$$[J_i, J_j] = i\hbar \epsilon_{ijk} J_k$$

are called angular momentum operators.

Rem: Assume we have three operators $A_i, i=1,2,3$, satisfying

$$[A_i, A_j] = \alpha \epsilon_{ijk} A_k$$

Then we can always redefine

$$J_i \equiv \frac{i\hbar}{\alpha} A_i$$

to get

$$\begin{aligned}
 [J_i, J_j] &= \left[\frac{i\hbar}{\alpha} A_i, \frac{i\hbar}{\alpha} A_j \right] \\
 &= \left(\frac{i\hbar}{\alpha} \right)^2 [A_i, A_j] \\
 &= \left(\frac{i\hbar}{\alpha} \right)^2 \alpha \epsilon_{ijk} A_k \\
 &= i\hbar \epsilon_{ijk} \underbrace{\frac{i\hbar A_k}{\alpha}}_{J_k} = i\hbar \epsilon_{ijk} J_k
 \end{aligned}$$

Given an angular momentum operator

$$\vec{J} = J_i \hat{e}_i, \quad [J_i, J_j] = \epsilon_{ijk} i\hbar J_k$$

for two arbitrary three-vectors. $\vec{a}, \vec{b} \in \mathbb{R}^3$
we form the products

$$\vec{a} \cdot \vec{J} = a_i J_i, \quad \vec{b} \cdot \vec{J} = b_i J_i$$

to have the identity

$$[\vec{a} \cdot \vec{J}, \vec{b} \cdot \vec{J}] = i\hbar (\vec{a} \times \vec{b}) \cdot \vec{J}$$

In fact, since \vec{a} and \vec{b} are not operators and always commute, we have

$$\begin{aligned}
 [\vec{a} \cdot \vec{J}, \vec{b} \cdot \vec{J}] &= a_i b_j [J_i, J_j] \\
 &= i\hbar \epsilon_{ijk} a_i b_j J_k = i\hbar (\vec{a} \times \vec{b})_k J_k \\
 &= i\hbar (\vec{a} \times \vec{b}) \cdot \vec{J}
 \end{aligned}$$

More Commutation Relations

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Given three operators J_i , $i=1,2,3$, satisfying

$$[J_i, J_j] = i\hbar \epsilon_{ijk} J_k$$

(i.e., given an angular momentum operator set J_i), we define the total angular momentum as

$$J^2 = J_1^2 + J_2^2 + J_3^2 = J_i J_i$$

Exercise: Show that

$$[J_i, J^2] = 0$$

solution:

$$\begin{aligned} [J_i, J_k J_k] &= J_k [J_i, J_k] + [J_i, J_k] J_k \\ &= i\hbar \epsilon_{ikl} J_k J_l + i\hbar \epsilon_{ikl} J_l J_k = 0 \end{aligned}$$

Therefore, the total angular momentum J^2 commutes with each of its three components J_i . Actually, we may prove the following more general

Proposition: If $[J_i, A_j] = i\hbar \epsilon_{ijk} A_k$ and

$[J_i, B_j] = i\hbar \epsilon_{ijk} B_k$, then

$$[J_i, \vec{A} \cdot \vec{B}] = 0$$

Proof: By direct computation

$$\begin{aligned}
 [J_i, A_j B_j] &= A_j [J_i, B_j] + [J_i, A_j] B_j \\
 &= i\hbar \epsilon_{ijk} A_j B_k + i\hbar \epsilon_{ijk} A_k B_j \\
 &= i\hbar (\epsilon_{ijk} + \epsilon_{ikj}) A_j B_k = 0
 \end{aligned}$$

Corollary:

(i) For general angular momentum J_i , we

have

$$[J^2, J_i] = 0, \quad i=1, 2, 3$$

(ii) For orbital angular momentum $\vec{L} = \vec{X} \times \vec{P}$

we have

{	$[L^2, L_i] = 0$	$(A_i = B_i = L_i)$
	$[P^2, L_i] = 0$	$(A_i = B_i = P_i)$
	$[X^2, L_i] = 0$	$(A_i = B_i = X_i)$
	$[\vec{X} \cdot \vec{P}, L_i] = 0$	$(A_i = X_i, B_i = P_i)$
	$[\vec{X} \cdot \vec{L}, L_i] = 0$	$(A_i = X_i, B_i = L_i)$
	$[\vec{P} \cdot \vec{L}, L_i] = 0$	$(A_i = P_i, B_i = L_i)$

Ladder Operators

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Given an angular momentum operator set J_i , $[J_i, J_j] = i\hbar \epsilon_{ijk} J_k$,
we define the corresponding ladder operators J_{\pm} as

$$J_{\pm} = J_1 \pm i J_2$$

Proposition: The ladder operators satisfy

$$(i) [J^2, J_{\pm}] = 0$$

$$(ii) J_{\mp} J_{\pm} = J^2 - (J_3^2 \pm \hbar J_3)$$

$$(iii) [J_+, J_-] = 2\hbar J_3$$

$$(iv) [J_3, J_{\pm}] = \pm \hbar J_{\pm}$$

Proof:

$$(i) [J^2, J_{\pm}] = [J^2, J_1 \pm i J_2] = 0$$

$$(ii) J_{\mp} J_{\pm} = (J_1 \mp i J_2)(J_1 \pm i J_2)$$

$$= J_1^2 + J_2^2 \pm i [J_1, J_2]$$

$$= J_1^2 + J_2^2 \mp \hbar J_3 = J^2 - (J_3^2 \pm \hbar J_3)$$

$$(iii) [J_+, J_-] = [J_1 + i J_2, J_1 - i J_2]$$

$$= -i [J_1, J_2] + i [J_2, J_1] = 2\hbar J_3$$

$$(iv) [J_3, J_{\pm}] = [J_3, J_1 \pm i J_2] = [J_3, J_1] \pm i [J_3, J_2]$$

corollary: Let ψ be a common J^2 and J_3 eigenvector

with $J^2\psi = \lambda\hbar^2\psi$ and $J_3\psi = m\hbar\psi$. Then

$$(i) \quad J^2 J_{\pm}\psi = \lambda\hbar^2 J_{\pm}\psi$$

$$(ii) \quad J_3 J_{\pm}\psi = (m \pm 1)\hbar J_{\pm}\psi$$

$$(iii) \quad \|J_{\pm}\psi\|^2 = [\lambda - m(m \pm 1)]\hbar^2 \|\psi\|^2$$

$$(iv) \quad \lambda \geq m(m \pm 1)$$

$$(v) \quad \lambda = m(m \pm 1) \text{ iff } J_{\pm}\psi = 0$$

proof:

$$(i) \quad \text{Since } [J^2, J_{\pm}] = 0 \text{ we have } J^2(J_{\pm}\psi) = J_{\pm}(J^2\psi) = J_{\pm}\hbar^2\lambda\psi$$

$$(ii) \quad J_3 J_{\pm}\psi = \left\{ \underbrace{[J_3, J_{\pm}]}_{\pm\hbar J_{\pm}} + J_{\pm} J_3 \right\} \psi$$

$$= (\pm\hbar J_{\pm} + m\hbar J_{\pm})\psi = (m \pm 1)\hbar J_{\pm}\psi$$

$$(iii) \quad \|J_{\pm}\psi\|^2 = \langle J_{\pm}\psi | J_{\pm}\psi \rangle$$

$$= \langle \psi | J_{\mp} J_{\pm} \psi \rangle$$

$$= \langle \psi | \{ J^2 - (J_3^2 \pm \hbar J_3) \} \psi \rangle = (\lambda^2 - m(m \pm 1))\hbar^2 \|\psi\|^2$$

$$(iv) \quad \text{Since } \|J_{\pm}\psi\|^2 \geq 0 \text{ we have } \lambda^2 - m(m \pm 1) \geq 0$$

$$(v) \quad J_{\pm}\psi = 0 \Leftrightarrow \|J_{\pm}\psi\|^2 = 0 \Leftrightarrow \lambda^2 - m(m \pm 1) = 0$$

Proposition: The eigenvalues of the total angular momentum operator J^2 are $j(j+1)\hbar^2$ with $j = 0, \frac{1}{2}, 1, \frac{3}{2}, 2, \dots$ -117-

For each seminteger j the corresponding eigenvalues of J_3 are $m\hbar$ with $m = -j, -j+1, \dots, j-1, j$.

Proof: Consider $\psi \in \mathcal{H}$ such that $J^2\psi = \lambda\hbar^2\psi$ and $J_3\psi = m\hbar\psi$ (this is possible because $[J_3, J^2] = 0$).

From $\lambda \geq m(m \pm 1)\hbar^2$ we have

$$\lambda + \frac{1}{4}\hbar^2 \geq m^2 \pm m + \frac{1}{4}\hbar^2 = \left(m \pm \frac{1}{2}\right)^2 \hbar^2.$$

That means, for a given λ , there exists a maximal and a minimal value for m . Note however that for a fixed given λ , application of the operators J_{\pm} in ψ raises and lowers m without affecting j :

$$J_3(J_+\psi) = (m+1)\hbar J_+\psi$$

$$\begin{aligned} J_3(J_+^2\psi) &= \left\{ [J_3, J_+] + J_+ J_3 \right\} J_+\psi \\ &= \left\{ \hbar J_+ + J_+(m+1)\hbar \right\} J_+\psi \\ &= \hbar(m+2) J_+^2\psi \end{aligned}$$

$$J_3(J_+^N\psi) = \hbar(m+N)\hbar(J_+^N\psi)$$

Thus there must exist a minimal natural $p \in \mathbb{N}$ such that

$$\mathcal{J}_+^{p+1} \psi = 0 \quad \text{with} \quad \mathcal{J}_+^p \psi \neq 0$$

and similarly from \mathcal{J}_- , a minimal natural $q \in \mathbb{N}$ such that

$$\mathcal{J}_-^{q+1} \psi = 0 \quad \text{with} \quad \mathcal{J}_-^q \psi \neq 0$$

That means we have

$$\left. \begin{array}{l} \mathcal{J}^2 \psi = \lambda h^2 \psi \\ \mathcal{J}_3 \psi = m h \psi \end{array} \right\} \left. \begin{array}{l} \mathcal{J}^2 \mathcal{J}_+^p \psi = \lambda h^2 \mathcal{J}_+^p \psi \\ \mathcal{J}_3 \mathcal{J}_+^p \psi = (m+p) h \mathcal{J}_+^p \psi \\ \quad \quad \quad M=m+p \quad \quad \quad M=m+p \end{array} \right\} \begin{array}{l} \mathcal{J}_+^p \psi \neq 0 \\ \mathcal{J}_+^{p+1} \psi = 0 \end{array}$$

recall

$$\mathcal{J}_+ \left(\mathcal{J}_+^p \psi \right) = 0 \Leftrightarrow \lambda = M(M+1) = (m+p)(m+p+1)$$

$$\boxed{\lambda = (m+p)(m+p+1)}$$

and similarly for the \mathcal{J}_- case:

$$\left. \begin{array}{l} \mathcal{J}^2 \psi = \lambda h^2 \psi \\ \mathcal{J}_3 \psi = m h \psi \end{array} \right\} \xrightarrow{\mathcal{J}_-^q} \left. \begin{array}{l} \mathcal{J}^2 \mathcal{J}_-^q \psi = \lambda h^2 \mathcal{J}_-^q \psi \\ \mathcal{J}_3 \mathcal{J}_-^q \psi = (m-q) h \mathcal{J}_-^q \psi \end{array} \right\} \begin{array}{l} \mathcal{J}_-^q \psi \neq 0 \\ \mathcal{J}_-^{q+1} \psi = 0 \end{array}$$

$$\mathcal{J}_- \left(\mathcal{J}_-^q \psi \right) = 0 \Leftrightarrow \lambda = M(M+1) = (m-q)(m-q-1)$$

$$\boxed{\lambda = (m-q)(m-q-1)}$$

Of course the two results for λ must be equal