

# The Bohm-Aharonov Effect

Recall the Lorentz force

$$\vec{F} = e\vec{E} + e\vec{v} \times \vec{B}$$

with

$$\begin{cases} \vec{E} = -\frac{\partial \vec{A}}{\partial t} - \nabla\phi \\ \vec{B} = \nabla \times \vec{A} \end{cases}$$

The potentials  $\vec{A}$  and  $\phi$  are not unique,  
given an arbitrary  $\chi$  real function

$$\chi(\vec{r}, t)$$

the potentials

$$\vec{A}' = \vec{A} - \nabla\chi$$

$$\phi' = \phi + \frac{\partial \chi}{\partial t}$$

leads to the same electromagnetic fields  $\vec{E}, \vec{B}$ .

Indeed

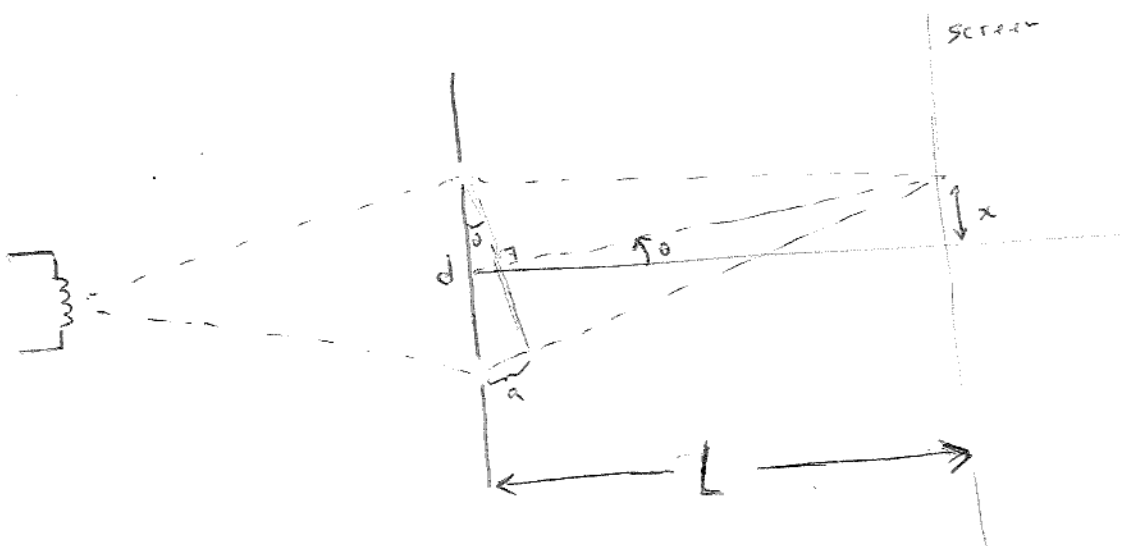
$$\begin{aligned} \vec{E}' &= -\frac{\partial \vec{A}}{\partial t} + \frac{\partial \vec{\nabla} \chi}{\partial t} - \vec{\nabla} \phi - \vec{\nabla} \frac{\partial \chi}{\partial t} \\ &= -\frac{\partial \vec{A}}{\partial t} - \vec{\nabla} \phi + \vec{\nabla} \left( \frac{\partial \chi}{\partial t} \right) - \vec{\nabla} \left( \frac{\partial \chi}{\partial t} \right) \\ &= -\frac{\partial \vec{A}}{\partial t} - \vec{\nabla} \phi = \vec{E} \end{aligned}$$

$$\begin{aligned} \vec{B}' &= \vec{\nabla} \times \vec{A} - \underbrace{\vec{\nabla} \times (\vec{\nabla} \chi)}_{\vec{0}} \\ &= \vec{\nabla} \times \vec{A} = \vec{B} \end{aligned}$$

Re-...

$$\begin{aligned} \epsilon_{ijk} \partial_j (\vec{\nabla} \chi)_k \hat{e}_i &= \\ = \underbrace{\epsilon_{ijk}}_{\text{ant}} \underbrace{\partial_j \partial_k}_{\text{sym}} \chi \hat{e}_i &= 0 \end{aligned}$$

Consider now the well known 2-slit experiment with an electron beam



By considering  $x, d \ll L$  we use the approximation

$$\tan \theta = \frac{x}{L} \approx \frac{a}{d}$$

So that  $a \approx \left(\frac{x}{L}\right) d$

Considering plane waves for the electron beam, the path difference is  $a$  and we have maxima when

$$\frac{a}{\lambda} = m$$

where  $\lambda$  is the wave length (the path difference must be a multiple of the wave length)

That is

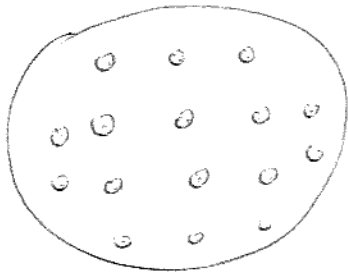
$$\frac{x d}{\lambda L} = m, \quad \boxed{x = m \frac{\lambda}{d} L}$$

The maxima occur on the screen for

$$x = m \frac{\lambda}{d} L \quad \left( x = 2\pi m \frac{\lambda L}{2\pi d} = \delta \frac{\lambda L}{2\pi d} \right)$$

while the minima occur in between

Now we introduce a solenoid behind the wall between the slits



Given a general vector  $\vec{A}$ , its rotational in cylindrical coordinates may be written as

$$\vec{\nabla} \times \vec{A} = \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right) \hat{r} + \left( \frac{\partial A_\phi}{\partial z} - \frac{\partial A_z}{\partial r} \right) \hat{\phi} + \frac{1}{r} \left[ \frac{\partial}{\partial r} (r A_\phi) - \frac{\partial A_r}{\partial \phi} \right] \hat{z}$$

Since we need  $\vec{B} = B \hat{z}$ , from  $\vec{B} = \vec{\nabla} \times \vec{A}$  we see we must have, for  $r < R$

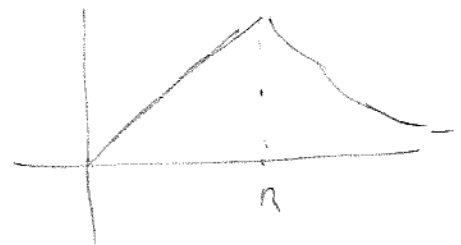
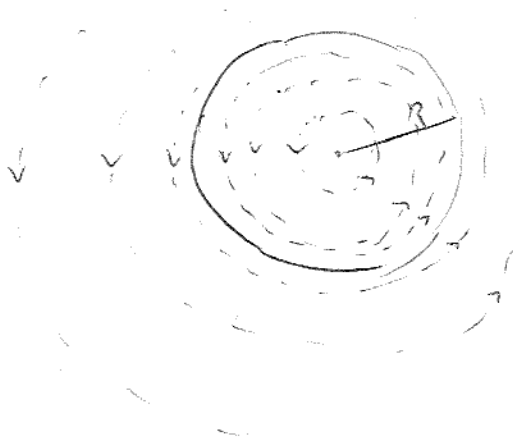
$$B \hat{z} = \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right) \hat{r} + \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) \hat{\phi} + \frac{1}{r} \left[ \frac{\partial}{\partial r} (r A_\phi) - \frac{\partial A_r}{\partial \phi} \right] \hat{z}$$

One possible solution is

$$A_r = A_z = 0, \quad A_\phi = \frac{B r}{2}, \quad r < R$$

For  $r \gg R$ , we must have  $\vec{B} = \vec{0}$ . Maintaining continuity for  $r = R$ , we may write

$$A_r = A_z = 0, \quad A_\phi = \frac{B R^2}{2r}$$



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The wave function for the free electron field is given by the plane wave

$$\begin{aligned}\psi &= C \exp\left(\frac{i}{\hbar} \vec{p} \cdot \vec{r}\right) \\ &= C \exp(i\alpha)\end{aligned}$$

with  $\alpha = \frac{\vec{p} \cdot \vec{r}}{\hbar}$  = phase.

We know the effect of turning on the electromagnetic field is given by

$$\vec{p} \rightarrow \vec{p} - e\vec{A}$$

which amounts in changing

$$\alpha \rightarrow \frac{\vec{p} \cdot \vec{r}}{\hbar} - \frac{e\vec{A} \cdot \vec{r}}{\hbar}$$

The change in phase over an entire trajectory

is

$$\Delta\alpha = -\frac{e}{\hbar} \int \vec{A} \cdot \vec{r}$$

= 52 =

Considering trajectories 1 and 2, we have

$$\Delta\alpha_1 = -\frac{e}{\hbar} \int_1 \vec{A} \cdot d\vec{r} \quad \Delta\alpha_2 = -\frac{e}{\hbar} \int_2 \vec{A} \cdot d\vec{r}$$

$$\Delta\delta = \Delta\alpha_1 - \Delta\alpha_2$$

$$= -\frac{e}{\hbar} \int_1 \vec{A} \cdot d\vec{r} + \frac{e}{\hbar} \int_2 \vec{A} \cdot d\vec{r}$$

$$= \frac{e}{\hbar} \oint \vec{A} \cdot d\vec{r}$$

$$= \frac{e}{\hbar} \int (\vec{\nabla} \times \vec{A}) \cdot \hat{n} dS$$

$$= \frac{e}{\hbar} \int \vec{B} \cdot \hat{n} dS$$

$$= \frac{e}{\hbar} \Phi$$

The interference pattern changes by

$$\Delta\alpha = \Delta\delta \frac{\lambda L}{2\pi d} = \frac{e}{\hbar} \frac{\lambda L}{2\pi d} \Phi$$

$$= 53 =$$

Considering the region  $r > R$ , we  
 have  $\vec{B} = \vec{\nabla} \times \vec{A} = \vec{0}$ , as we already  
 saw

$$A_\phi = \frac{BR^2}{2r} \quad , \quad A_r = A_\theta = 0$$

From  $\vec{A} = \vec{\nabla} \chi$ , we have

$$A_\phi = \frac{1}{r} \frac{\partial \chi}{\partial \phi} = \frac{BR^2}{2r}$$

$$\chi = \frac{BR^2 \phi}{2}$$

and  $\chi$  is not a "single-valued" in  
 space function

$$\Delta \Phi = \Delta \alpha_1 - \Delta \alpha_2$$

$$= \frac{e}{h} \oint \vec{A} \cdot d\vec{r}$$

$$= \frac{e}{h} \oint (\vec{\nabla} \chi) \cdot d\vec{r} = \frac{e}{h} \chi \Big|_0^{2\pi} = \frac{e}{h} \frac{BR^2 2\pi}{2}$$

$$= \frac{e}{h} \Phi$$

$$= 54 =$$



We know that if  $\vec{A} = \vec{\nabla} \chi$  everywhere then we would have  $\vec{B} = \vec{\nabla} \times \vec{A} = \vec{\nabla} \times (\vec{\nabla} \chi) = \vec{0}$  everywhere. But that is not possible.

We consider now the problem defined only in the region  $r \geq R$  with  $R > 0$ . Then we may have

$$\left\{ \begin{array}{l} \vec{A} = \vec{\nabla} \chi, \quad r \geq R \\ \vec{B} = \vec{\nabla} \times \vec{A} = \vec{\nabla} \times (\vec{\nabla} \chi) = \vec{0}, \quad r \geq R \end{array} \right.$$

In fact we have seen we may take in cylindrical coordinates

$$\chi(r, \phi, z) = \frac{BR^2 \phi}{2}$$

this leads to

$$\vec{A} = \hat{r} \frac{\partial}{\partial r} + \hat{\phi} \frac{1}{r} \frac{\partial}{\partial \phi} + \hat{z} \frac{\partial}{\partial z}$$

$$\vec{A} = \frac{BR^2}{2r} \hat{\phi}$$

~~$$\vec{A} = \frac{BR^2}{2} \hat{\phi} = \frac{BR^2}{2} \hat{\phi}$$~~

$$\left( A_r = A_z = 0, A_\phi = \frac{BR^2}{2r} \right)$$

and

$$\vec{B} = \vec{\nabla} \times \vec{A} \quad , \quad n \geq 1$$

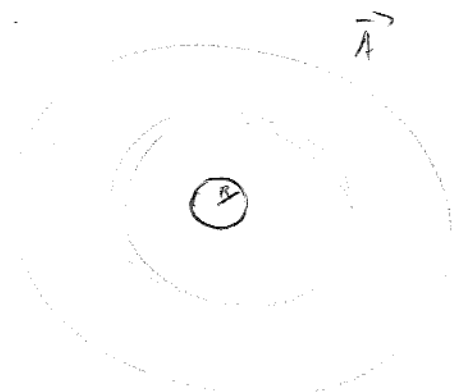
$$= \left( \frac{1}{r} \frac{\partial A_\phi}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right) \hat{r} +$$

$$+ \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) \hat{\phi} + \frac{1}{r} \left[ \frac{\partial}{\partial r} (r A_\phi) - \frac{\partial A_r}{\partial \phi} \right] \hat{z}$$

$$= -\frac{\partial}{\partial z} \left( \frac{B R^2}{2n} \right) \hat{r} + \frac{1}{r} \frac{\partial}{\partial r} \left( \frac{B R^2}{2} \right) \hat{z}$$

$$= \vec{0} \quad , \quad n \geq 1$$

That is,  $\vec{B} \equiv \vec{0}$  for  $n \geq 1$



Now observe that  $\chi(r, \phi, z) = \chi(\phi) = \frac{BR^2\phi}{2}$

is not a single-valued function:

We have already calculated the change in phase for the electron as

$$\begin{aligned}
 \Delta S &= \Delta \chi_1 + \Delta \chi_2 \\
 &= \frac{e}{\hbar} \oint \vec{A} \cdot d\vec{r} \\
 &= \frac{e}{\hbar} \int (\vec{\nabla} \times \vec{A}) \cdot \hat{n} dS \quad \leftarrow \text{for } r < R \\
 &= \frac{e}{\hbar} \int \vec{B} \cdot \hat{n} dS \quad \leftarrow \text{for } r < R \\
 &= \frac{e}{\hbar} \Phi
 \end{aligned}$$

where  $\Phi$  was the magnetic flux. Since we want to consider now only the region  $r > R$ , we must have for consistency:

$$\begin{aligned}
 \frac{e}{\hbar} \Phi &= \Delta S = \frac{e}{\hbar} \oint \vec{A} \cdot d\vec{r} = \frac{e}{\hbar} \oint \vec{\nabla} \chi \cdot d\vec{r} \\
 &= \frac{e}{\hbar} \chi \Big|_0^{2\pi} = \frac{e}{\hbar} \frac{BR^2}{2} 2\pi
 \end{aligned}$$

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Thus we see, for consistency,  $\chi$  is not single-valued in the sense that the value of the integral

$$\oint \vec{A} \cdot d\vec{n}$$

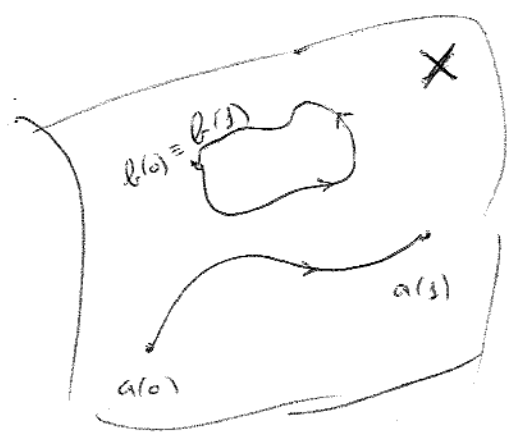
depends whether the path passes through the pole, in which ~~same~~ direction (clockwise or counterclockwise) and depends on how many times it circles through.

That leads us to the interesting subject of topology.

A path  $\alpha$  in a topological space  $X$  is a continuous function  $\alpha(s)$  of a real parameter  $s$ . We may restrict this definition to let the parameter  $s$  vary in the interval  $[0, 1]$

$$\alpha : [0, 1] \rightarrow X$$

We may have both closed or open paths



Two paths  $\alpha$  and  $\beta$  are said to be homotopic when there exists a continuous function  $L(t, s)$  such that

with the same initial and final points  
 $x_0 = \alpha(0) = \beta(0)$   
 $x_1 = \alpha(1) = \beta(1)$

$$L(0, s) = \alpha(s)$$

$$L(1, s) = \beta(s)$$

Path homotopy is an equivalence relation.

In this case we write  $\alpha \sim \beta$

Given a path  $a: [0, 1] \rightarrow X$  we define its inverse  $a^{-1}: [0, 1] \rightarrow X$  by

$$a^{-1}(s) = a(1-s)$$

Given two paths  $a$  and  $b$  with  $a(1) = b(0)$  we define the product path

$c = ab$  by

$$c(s) = \begin{cases} a(2s), & 0 \leq s \leq \frac{1}{2} \\ b(2s-1), & \frac{1}{2} < s \leq 1 \end{cases}$$

The product of curves induces a product in the set of equivalence classes of curves in  $X$  (this product is not always ~~well~~ defined).

Def.: Let  $X$  be a top space and  $x_0 \in X$ .

A path which begins and ends at  $x_0$  is

a loop based on  $x_0$ . The set of homotopy

classes of loops based on  $x_0$  constitutes a

group under the previously defined product. This

is the fundamental group of  $X$  relative to base

point  $x_0$ , denoted  $= \pi_1(X, x_0)$ .

# The Yang-Mills Field

We recall we had a Lagrangian density

$$\mathcal{L} = \underbrace{\partial_\mu \phi} \partial^\mu \phi^* - m^2 \phi^* \phi$$

which could be rewritten as

$$\mathcal{L} = (\underbrace{\partial_\mu \phi}_{\sim}) \cdot (\underbrace{\partial^\mu \phi^*}_{\sim}) - m^2 \underbrace{\phi}_{\sim} \cdot \underbrace{\phi}_{\sim}$$

with

$$\phi = (\phi_1 + i \phi_2) / \sqrt{2}$$

$$\phi^* = (\phi_1 - i \phi_2) / \sqrt{2}$$

and

$$\underbrace{\phi}_{\sim} = \hat{n} \phi_1 + \hat{j} \phi_2$$

and which was globally invariant under  $SO(2)$

$$\begin{pmatrix} \phi_1' \\ \phi_2' \end{pmatrix} = \begin{pmatrix} \cos \Lambda & \sin \Lambda \\ -\sin \Lambda & \cos \Lambda \end{pmatrix} \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix}$$

$$\phi' = e^{i\Lambda} \phi$$

$$\phi^{*'} = e^{-i\Lambda} \phi^*$$

$$= GI =$$

By introducing the gauge field  $A_\mu$  we have obtained the total Lagrangian density

$$\mathcal{L}_0 = (D_\mu \phi) (D^\mu \phi^*) - m^2 \phi^* \phi - \frac{1}{4} F_{\mu\nu} F^{\mu\nu}$$

with  $D_\mu \equiv \partial_\mu + ie A_\mu$

which is locally invariant under either

finite transfs:

$$A_\mu \rightarrow A'_\mu = A_\mu + \frac{1}{e} \partial_\mu \Lambda$$

$$\phi \rightarrow \phi' = e^{-i\Lambda} \phi$$

$$\phi^* \rightarrow \phi'^* = e^{i\Lambda} \phi^*$$

infinitesimal transfs:

$$\delta A_\mu = \frac{1}{e} \partial_\mu \Lambda$$

$$\delta \phi = -i\Lambda \phi$$

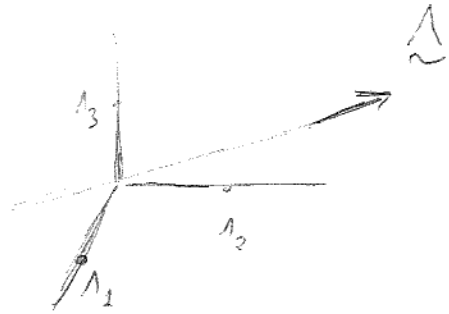
$$\delta \phi^* = i\Lambda \phi^*$$

The idea now is to generalize from the group  $U(1) \cong SO(2)$  to  $SO(3)$ .



Consider an internal space, three dimensional,  
 for the field  $\phi$ . An infinitesimal rotation  
 may be described by

$$\hat{\Lambda} = \Lambda_1 \hat{e}_1 + \Lambda_2 \hat{e}_2 + \Lambda_3 \hat{e}_3$$



Since the rotation is infinitesimal,

~~(1 + i \Lambda\_k L\_k)~~

$$\begin{aligned} & \left(1 + \frac{i}{\hbar} \Lambda_1 L_1\right) \left(1 + \frac{i}{\hbar} \Lambda_2 L_2\right) \left(1 + \frac{i}{\hbar} \Lambda_3 L_3\right) = \\ & = \left(1 + \frac{i}{\hbar} \Lambda_k L_k\right) \end{aligned}$$

The field  $\phi = \phi_k \hat{e}_k$  transforms as

$$\begin{aligned} \phi_{\sim} & \rightarrow \phi'_{\sim} = \exp \left[ 1 + \frac{i}{\hbar} \Lambda_k L_k \right] \phi_{\sim} \\ & = \phi_{\sim} + \frac{i}{\hbar} \Lambda_k L_k \phi_{\sim} \end{aligned}$$

Thus, in components we have

$$\begin{aligned}
\phi_j' &= \phi_j + \frac{i}{\hbar} \Lambda_k (L_k \phi)_j \\
&= \phi_j + \frac{i}{\hbar} \Lambda_k (L_k)_{ji} \phi_i \\
&= \phi_j + \frac{i}{\hbar} \Lambda_k (-i\hbar \epsilon_{kji}) \phi_i \\
&= \phi_j + \epsilon_{kji} \Lambda_k \phi_i \\
&= \phi_j + \epsilon_{jki} \Lambda_k \phi_i \\
&= \phi_j - (\underline{\Lambda} \times \underline{\phi})_j
\end{aligned}$$

A bit more compact, this can be rewritten as

$$\underline{\phi} \rightarrow \underline{\phi}' = \underline{\phi} - \underline{\Lambda} \times \underline{\phi}$$

Since the infinitesimal parameter  $\underline{\Lambda}$  does not depend on space time we have a global symmetry (or: gauge transf. of the first kind).

The group of symmetries is  $SO(3)$  and look forward in generalizing it to a local gauge transf.

Note that, if we let  $\Lambda$  depend on space time, we have

$$\phi \rightarrow \phi' = \phi - \Lambda \times \phi$$

$$\partial_\mu \phi \rightarrow \partial_\mu \phi' = \partial_\mu \phi - \Lambda \times \partial_\mu \phi - \partial_\mu \Lambda \times \phi$$

which means

$$\delta(\partial_\mu \phi) = -\Lambda \times \partial_\mu \phi - \partial_\mu \Lambda \times \phi$$

and  $\partial_\mu \phi$  does not transform covariantly.

We introduce a new gauge field  $W_\mu$  and the covariant derivative

$$D_\mu \phi = \partial_\mu \phi + g W_\mu \times \phi$$

requiring that

$$\delta(D_\mu \phi) = -\Lambda \times (D_\mu \phi)$$

So, on one hand we have

$$\delta(D_{\tilde{r}}\phi) = -\tilde{\Lambda} \times D_{\tilde{r}}\phi$$

and on the other hand

$$\delta(D_{\tilde{r}}\phi) = \delta\left[\partial_{\tilde{r}}\phi + g\tilde{W}_{\tilde{r}} \times \phi\right]$$

$$= \delta(\partial_{\tilde{r}}\phi) + g(\delta\tilde{W}_{\tilde{r}}) \times \phi + g\tilde{W}_{\tilde{r}} \times (\delta\phi)$$

$$= -\tilde{\Lambda} \times \partial_{\tilde{r}}\phi - \partial_{\tilde{r}}\tilde{\Lambda} \times \phi + g(\delta\tilde{W}_{\tilde{r}}) \times \phi +$$

$$-g\tilde{W}_{\tilde{r}} \times (\tilde{\Lambda} \times \phi)$$

$$= -\tilde{\Lambda} \times \partial_{\tilde{r}}\phi - \partial_{\tilde{r}}\tilde{\Lambda} \times \phi + g(\delta\tilde{W}_{\tilde{r}}) \times \phi +$$

$$-g(\tilde{W}_{\tilde{r}} \times \tilde{\Lambda}) \times \phi - g\tilde{\Lambda} \times (\tilde{W}_{\tilde{r}} \times \phi)$$

$$= -\tilde{\Lambda} \times (D_{\tilde{r}}\phi) + \left[ g\delta\tilde{W}_{\tilde{r}} - \partial_{\tilde{r}}\tilde{\Lambda} - g(\tilde{W}_{\tilde{r}} \times \tilde{\Lambda}) \right] \times \phi$$

From which we get the sufficient condition

$$\delta\tilde{W}_{\tilde{r}} = -\tilde{\Lambda} \times \tilde{W}_{\tilde{r}} + \frac{1}{g}\partial_{\tilde{r}}\tilde{\Lambda}$$

We have introduced the field  $\tilde{W}_\mu$  generalizing  $A_\mu$ . Now we generalize the field strength tensor  $F_{\mu\nu}$ .

The tensor  $\tilde{W}_\mu$  will be a vector under  $SO(3)$  and must transform as

$$\delta(\tilde{W}_\mu) = -\tilde{\Lambda} \times \tilde{W}_\mu$$

First note that

$$\delta[\partial_\mu \tilde{W}_\nu - \partial_\nu \tilde{W}_\mu] =$$

$$= \partial_\mu \left( -\tilde{\Lambda} \times \tilde{W}_\nu + \frac{1}{g} \partial_\nu \tilde{\Lambda} \right) - \partial_\nu \left( -\tilde{\Lambda} \times \tilde{W}_\mu + \frac{1}{g} \partial_\mu \tilde{\Lambda} \right)$$

$$= - \left( \partial_\mu \tilde{\Lambda} \times \tilde{W}_\nu - \partial_\nu \tilde{\Lambda} \times \tilde{W}_\mu \right) - \tilde{\Lambda} \times \left( \partial_\mu \tilde{W}_\nu - \partial_\nu \tilde{W}_\mu \right) +$$

$$+ \frac{1}{g} \left( \partial_\mu \partial_\nu \tilde{\Lambda} - \partial_\nu \partial_\mu \tilde{\Lambda} \right)$$

$$= -\tilde{\Lambda} \times \left( \partial_\mu \tilde{W}_\nu - \partial_\nu \tilde{W}_\mu \right) - \left( \partial_\mu \tilde{\Lambda} \times \tilde{W}_\nu - \partial_\nu \tilde{\Lambda} \times \tilde{W}_\mu \right)$$

$$= 6.7 =$$

secondly note that

$$\begin{aligned} \delta [g W_{\mu} \times W_{\nu}] &= g [-\Lambda \times W_{\mu} + \frac{1}{g} \partial_{\mu} \Lambda] \times W_{\nu} + \\ &\quad + g W_{\mu} \times [-\Lambda \times W_{\nu} + \frac{1}{g} \partial_{\nu} \Lambda] \\ &= -g \Lambda \times (W_{\mu} \times W_{\nu}) + \partial_{\mu} \Lambda \times W_{\nu} - \partial_{\nu} \Lambda \times W_{\mu} \end{aligned}$$

So we define

$$\bar{W}_{\mu\nu} \equiv \partial_{\mu} \bar{W}_{\nu} - \partial_{\nu} \bar{W}_{\mu} + g \bar{W}_{\mu} \times \bar{W}_{\nu}$$

and we have

$$\delta \bar{W}_{\mu\nu} = -\bar{\Lambda} \times \bar{W}_{\mu\nu}$$

And so

$$\bar{W}_{\mu\nu} \cdot \bar{W}^{\mu\nu}$$

is a scalar under  $SO(3)$ . Finally we

write the Lagrangian density as

$$\begin{aligned} \mathcal{L} &= \frac{1}{2} (D_{\mu} \bar{\phi}) \cdot (D^{\mu} \bar{\phi}) - \frac{m^2}{2} \bar{\phi} \cdot \bar{\phi} + \\ &\quad - \frac{1}{4} \bar{W}_{\mu\nu} \cdot \bar{W}^{\mu\nu} \\ &= \mathcal{L} = \end{aligned}$$

The total gauge invariant Lagrangian reads

$$\mathcal{L} = \frac{1}{2} (\mathbb{D}_\mu \bar{\Phi}) \cdot (\mathbb{D}^\mu \bar{\Phi}) - \frac{m^2}{2} \bar{\Phi} \cdot \bar{\Phi} - \frac{1}{4} \overline{W}_{\mu\nu} \cdot \overline{W}^{\mu\nu}$$

with  $\overline{W}_{\mu\nu} = \partial_\mu W_\nu - \partial_\nu W_\mu + g W_\mu \times W_\nu$

and  $\mathbb{D}_\mu \bar{\Phi} = \partial_\mu \bar{\Phi} + g W_\mu \times \bar{\Phi}$

The eqs of motion can be obtained from

$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial (W_\mu^i)} &= (\mathbb{D}_\nu \bar{\Phi})^j \frac{\partial (g W_\nu \times \bar{\Phi})^i}{\partial (W_\mu^i)} - \frac{1}{2} \overline{W}_{\mu\nu}^j \frac{\partial \overline{W}^{\mu\nu}}{\partial W_\mu^i} \\ &= (\mathbb{D}_\nu \bar{\Phi})^j \frac{\partial g \epsilon^{ijk} W_\nu^k \bar{\Phi}^i}{\partial (W_\mu^i)} - \frac{1}{2} \overline{W}_{\mu\nu}^j \frac{\partial g \epsilon^{jkl} W_\mu^k W_\nu^l}{\partial W_\mu^i} \\ &= (\mathbb{D}_\nu \bar{\Phi})^j g \epsilon^{jil} \bar{\Phi}^l - \overline{W}_{\mu\nu}^j g \epsilon^{jil} W^{\nu l} \\ &= -g \epsilon^{ijl} (\mathbb{D}_\nu \bar{\Phi})^j \bar{\Phi}^l + g \epsilon^{ijl} \overline{W}_{\mu\nu}^j W^{\nu l} \\ &= -g [(\mathbb{D}_\nu \bar{\Phi}) \times \bar{\Phi}]_i + g [\overline{W}_{\mu\nu} \times W^\nu]_i \\ &= 0 = \end{aligned}$$